

Fall 2012 Robotics Competition

Roboticists, the Global Ocean Exploration Scientists, GOES, needs your help exploring the Atlantic Ocean! Using their SeaBots, GOES is continually making discoveries in the oceans that aid and improve our lives, and from GOES discoveries, we are keeping our oceans, seas, and gulfs much healthier. GOES needs you to build a robot to deploy the SeaBots in the North and South Atlantic Oceans. Please help GOES explore the Atlantic!

Below is everything that we know about the mission.

- The team must be ready to execute the mission for your EARLY Tournament.
- The equipment available for a team to build a robot is 3 LEGO® Simple & Motorized Mechanisms Kits.
- The following diagram presents the environment that will be encountered. Construction details are found in the *Mission Field Details* document.

Field 48" x 48" ¹/₂" Plywood

Field Perimeter 2" x 4" Boards

North America
(Home)
15" x 15"
10" from Left Border

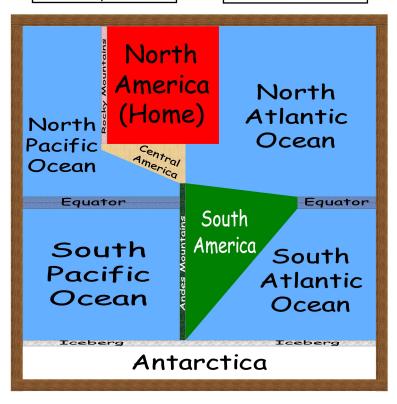
Rocky Mountains $\frac{3}{4}$ " $\times \frac{1}{4}$ " Molding

Central America 10¾" × 5" ¾" Plywood

> South America 15" × 20"

Andes Mountains $\frac{3}{4}$ " $\times \frac{1}{4}$ " Molding

Antarctica 45" × 5"



North Pacific Ocean $20'' \times 21\frac{3}{4}''$

North Atlantic Ocean 25" × 21¾"

Equator
2 strips
3" × 1" Molding
Centered between
Top & Bottom Borders

South Pacific Ocean $20" \times 16\frac{3}{4}"$

South Atlantic Ocean $25'' \times 16\frac{3}{4}''$

Iceberg $\frac{3}{4}$ " $\times \frac{1}{4}$ " Molding

Western Hemisphere

• The following diagram presents where the *SeaBots* and *Carriers* will be in the Western Hemisphere. Seabed Carrier Atmosphere Carrier Midnight Carrier Twilight Carrier Abyss Carrier Sunlight Carrier Trench Carrier

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Mission Rules

- 1. The team has 2 minutes to complete the mission.
- 2. There are 76 **SeaBots** on the playing field at the beginning of each mission, represented by dice. Dice details are found in the **Mission Object Details** document.
- 3. There are 7 **SeaBot Carriers** on the playing field at the beginning of the mission constructed from one LEGO® Simple & Motorized Mechanisms kit. Carrier details are in each **Carrier Instruction** document.
- 4. The team's score is determined at the end of the 2-minute mission.
- 5. If a **SeaBot** is moving when time expires, the **SeaBot**'s scoring position is determined when the **SeaBot** has come to rest.
- 6. There are two scoring zones: the NORTH ATLANTIC OCEAN and SOUTH ATLANTIC OCEAN.
- 7. The goal of the mission is to evenly *deploy SeaBots* amongst the North Atlantic Ocean and South Atlantic Ocean.
- 8. A **SeaBot** is **deployed** when the **SeaBot** is directly supported by the field or other **SeaBots** that are **deployed**. A **SeaBot** is **NOT deployed** if it is on a **Carrier** or in a robot, which is different than in previous EARLY missions.
- 9. The team scores 2 points for each SeaBot that is deployed in a scoring zone that has a corresponding SeaBot deployed in the other scoring zone. Therefore, each of these evenly deployed SeaBot Pairs is worth 4 points.
- 10. The team scores 1 point for each **SeaBot** that is **deployed** in a scoring zone and is not part of a **SeaBot Pair**
- 11. There is one penalty zone: ANTARCTICA. The ICEBERG is part of ANTARCTICA.
- 12. The team is penalized 3 points for each SeaBot deployed in ANTARCTICA.
- 13. A perfect score is achieved by having 38 *deployed SeaBots* in each of the two scoring zones. Thereby, all 76 *SeaBots* are part of 38 *SeaBot Pairs* resulting in a score of 76x2=152 or 38x4=152. In contrast, if all 76 *SeaBots* are *deployed* in one scoring zone, the resulting score is 76x1=76.
- 14. A SeaBot deployed and breaking the plane of a scoring zone is considered deployed in the scoring zone.
- 15. A **SeaBot** deployed in multiple zones simultaneously (scoring zone & non-scoring zone, scoring zone & penalty zone, penalty zone & non-scoring zone, etc.) is considered deployed in the zone that results in the greatest points.
- 16. A SeaBot deployed on the Atlantic Equator is considered deployed in the scoring zone (North Atlantic Ocean) or South Atlantic Ocean) that results in the greatest points.
- 17. Please remember that a **SeaBot** must be "**deployed**" in a scoring zone for a **SeaBot** to count for points. A **SeaBot** is **deployed** when the **SeaBot** is directly supported by the field or other **SeaBots** that are **deployed**.

- 18. Only the parts that are contained in three LEGO® Simple & Motorized Mechanisms kits along with nine 20" controller extension wires may be used to construct the robot and attachments (i.e. no other materials such as glue may be used on the robot). The kit parts may not be altered.
- 19. HOME is the 15" x 15" boundary extended vertically. The ROCKY MOUNTAINS are part of HOME.
- 20. The robot and all attachments must begin completely inside **HOME** at the beginning of the 2-minute mission (i.e. no LEGO parts may be off the playing field when the mission begins). The parts do not have to be assembled together and the parts may be removed from and returned to the field during the 2-minute mission.
- 21. The team may retrieve their robot without penalty when the robot is partially inside **HOME** by lifting the robot vertically. After retrieving, the robot must be returned to **HOME**. If a **SeaBot** or **Carrier** remains with the robot when the robot is retrieved without penalty, the **SeaBot** or **Carrier** that is now in **HOME** remains in play.
- 22. If a team touches their robot, including parts that have become separated from the robot, that is completely outside HOME, a penalty of 10 points shall be assessed. The robot must be returned HOME to continue the mission and if a *SeaBot* or *Carrier* remains with the robot when the robot is returned HOME, the *SeaBot* or *Carrier* is removed from play.
- 23. The robot must start completely inside **HOME** every time the robot is returned **HOME** (i.e. after retrieving the robot, no part of the robot may be breaking the **HOME** plane when continuing the mission).
- 24. The controllers and wires are NOT considered part of the robot.
- 25. The controller wires may only be used to provide electrical power to robot motors (i.e. the controller wires may not be used to drag or corral a robot, *SeaBot* or *Carrier*). If a controller wire is used illegally (referee's judgment), the robot must immediately be returned **HOME** to continue the mission.
- 26. The robot shall not have any elastic stored energy when the mission begins or when the robot is returned **HOME**, but elastic stored energy may be created with a motor during the mission (i.e. the robot may not be manually "wound up").
- 27. The team may touch a **SeaBot** or **Carrier** without penalty if the **SeaBot** or **Carrier** is COMPLETELY inside the **HOME**.
- 28. If a *Carrier* is illegally touched, the *Carrier* along with any *SeaBots* it is carrying will be removed from the field. If a *SeaBot* is illegally touched, the *SeaBot* will be removed from the field.
- 29. A Carrier is never considered part of the robot.
- 30. **SeaBots** may only leave **HOME** by using the robot or by "letting go" of either a **SeaBot** or something carrying a **SeaBot**. For example, a team member may not roll, push, or throw a **SeaBot** but a team member may put a **SeaBot** on a 'LEGO slide' and "let go" of the **SeaBot**.
- 31. Because *SeaBots* are very valuable, if a *SeaBot* is ejected from the playing field, a penalty of 10 points shall be assessed. No penalty shall be assessed for a *SeaBot* that is removed by a referee.
- 32. A score of zero shall be awarded if penalties result in a negative score.
- 33. All referees' rulings are final.

Please contact <u>Mission.Control@EARLYrobotics.org</u> with any questions or comments. Thank you for maintaining the spirit of the game!